1	Observations of an Inertial Peak in the Intrinsic
2	Wind Spectrum Shifted by Rotation in the
3	Antarctic Vortex
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Abstract

23	Spectral analyses of time series of zonal winds derived from locations of balloons drifting
24	in the southern hemisphere polar vortex during the VORCORE campaign of the
25	STRATÉOLE program reveal a peak with a frequency near 0.10 hr ⁻¹ , more than 25%
26	higher than the inertial frequency at locations along the trajectories. Using balloon data
27	and values of relative vorticity evaluated from the Modern Era Retrospective-analyses for
28	Research and Applications (MERRA), we find that the spectral peak near 0.10 hr ⁻¹ can be
29	interpreted as due to inertial waves propagating inside the Antarctic polar vortex. In
30	support of our claim, we examine the way in which the low-frequency part of the gravity
31	wave spectrum sampled by the balloons is shifted due to effects of the background flow
32	vorticity. Locally, the background flow can be expressed as the sum of solid body
33	rotation and shear. We demonstrate that while pure solid body rotation gives an effective
34	inertial frequency equal to the absolute vorticity, the latter gives an effective inertial
35	frequency that varies, depending on the direction of wave propagation, between limits
36	defined by the absolute vorticity plus or minus half of the background relative vorticity.

38 1. Introduction

39 In an atmosphere at rest, the frequency spectrum of internal gravity waves is bounded 40 above by the Brunt-Väisälä frequency and below by the inertial frequency given by the 41 local value of the Coriolis parameter $f = 2\Omega \sin \varphi$, where φ is latitude and Ω is the angular speed of the Earth's rotation (24 hour)⁻¹. Inertial gravity waves with lower 42 43 frequencies are evanescent and have very short attenuation lengths (Eckart 1960). 44 Atmospheric measurements in Earth-fixed coordinate frames, e.g., time series of 45 stratospheric winds and electric fields, typically show a spectral peak near the inertial 46 frequency (Thompson 1978; Sidi and Barat 1986; Hu and Holzworth 1997). In some 47 cases, however, spectral peaks have been observed at frequencies ~3-20% higher than the 48 inertial frequency. The source of these frequency shifts is not yet fully understood; it has 49 been suggested that Doppler and stratification effects contribute to the shifts (Mori et al. 50 1990). It has also been suggested that rotational effects originating the vorticity of the 51 background flow might contribute to higher inertial frequencies [Kunze, 1985; Jones 52 2005; Lee and Eriksen, 1997] and that these effects might be instrumental in trapping 53 near inertial waves in vorticity minima (centers of anticyclonic motion) [Lee and Eriksen, 1997]. Plougonven and Zeitlin [2005] suggest a source of near inertial waves generated 54 55 by the geostrophic adjustment process. 56

Shifts in the spectral peak have also been reported in the spectrum of horizontal velocity
inferred from location time series of three super-pressure balloons (SPBs) released during
the Arctic Kiruna 2002 Campaign (Broutman et al. 2004, Hertzog and Vial 2001). The

spectral peak for two of the balloons in that campaign was slightly higher (5-10%) than the inertial frequency (Hertzog et al. 2002). These shifts cannot be due to Doppler effects since measurements made on drifting balloons are recorded in a quasi-Lagrangian reference frame. The spectrum corresponding to a third balloon in the Arctic Kiruna 2002 campaign lacked the near-inertial spectral peak, a feature attributed to differences in the magnitude of meridional excursions, implying significant variations of the Coriolis parameter along that balloon's trajectory.

66 In the present paper we examine the spectrum of zonal wind speeds derived from location 67 time series of SPBs released in the lower stratosphere during the austral spring of 2005 68 by the VORCORE Antarctic campaign. One of VORCORE's principal objectives was an 69 improved understanding of the gravity wave field in the Antarctic polar vortex. The SPBs 70 released by VORCORE drifted for several months at two isopycnic levels corresponding 71 approximately to either 50 hPa or 70 hPa. The inertial frequencies corresponding to the latitudes of the SPB locations range from 0.075 hr⁻¹ at 65°S to 0.083 hr⁻¹ at 90°S (based 72 on $f = 2\Omega \sin \phi$). However, the data analysis obtains a spectral peak near 0.10 hr⁻¹, more 73 74 than 25% higher than the largest value of the inertial frequency. We suggest that such a 75 shift to higher frequencies in the spectral peak is consistent with the effects of the relative 76 vorticity of the background flow on the inertial gravity wave field. The effects of the 77 background relative vorticity cannot be ignored in the dispersion relation of the gravity 78 wave field. For example, it has been shown that for some specified configurations of the 79 background flow the lower bound of the inertial wave spectrum is shifted by a substantial 80 fraction of the relative vorticity (Kunze 1985; Kunze and Boss 1998; Jones, 2005). We 81 study these effects for the background flows in which the SPBs drifted during the

VORCORE campaign. Our principal finding is that the spectral peak near 0.10 hr⁻¹ can be 82 83 interpreted as due to inertial waves influenced by the relative vorticity of the background 84 flow inside the Antarctic polar vortex. We show that features of the observed spectra are 85 consistent with relative vorticity expressed as the sum of solid body rotation and shear. 86 An outline of the paper is as follows. We begin with an overview of the effects of 87 rotation on the gravity wave dispersion relation and the location of the inertial peak (effective inertial frequency). Next, we describe the data sets used, present the results of 88 89 the data analysis, and compare the observed spectra with the calculated effective inertial 90 frequency which has contributions from both curvature and shear in the vortex. A 91 discussion of the results and limitations of the analysis concludes the paper. A detailed 92 analysis of how relative vorticity influences the effective inertial peak for waves 93 propagating in a rotating and sheared background is given in the appendix.

94 2. Theory of inertial gravity waves in rotational background95 flow

96 In a background state at rest, the approximate dispersion relation for low frequency
97 gravity waves is

98
$$m^2 = \frac{N^2}{\omega^2 - f^2} k^2 - \frac{1}{4H^2}$$
(1)

99 Here *m* is the vertical wavenumber, *k* is the horizontal wavenumber, ω is wave frequency, 100 N^2 is the square of the Brunt-Väisälä frequency, and *H* is the scale height. For $\omega < f$, m^2 101 is less than zero and the wave is evanescent. The inertial-gravity wave spectrum is cut off 102 for frequencies below *f*.

In a background state not at rest, its effects on the gravity wave dispersion relation are considered in two steps. The first step includes translational effects on wave frequency by replacing ω with the intrinsic frequency $\omega_l = k (c - U_k)$, where *c* is the phase speed, *k* is the magnitude of the horizontal wavenumber vector *k*, and U_k is the component of the background flow projected on *k*. The frequency seen by a drifting balloon is approximately the intrinsic frequency (Hertzog and Vial 2001).

109 The second step includes rotational effects. This is illustrated for the simple case in 110 which the background velocity field is constant angular velocity $\overline{\Omega} = (\overline{\zeta}/2)\hat{z}$, where $\overline{\zeta}$ is 111 the background vorticity assumed to be constant and \hat{z} is the vertical unit vector around 112 the vertical axis (solid body rotation). In a frame of reference rotating with the flow, and 113 hence with angular velocity $\overline{\Omega} = (\overline{\zeta}/2)\hat{z}$, the horizontal velocity in reference to Earth, **u**, 114 is given by

115

116
$$\mathbf{u} = \Omega \mathbf{u}' + \mathbf{r}' \times \mathbf{u}'$$
 (2)

117 where \mathbf{u}' is the deviation from the background flow, and \mathbf{r}' is the position vector. The 118 fluid acceleration in reference to Earth $d\mathbf{u}/dt$ is given by

119
$$\frac{d\mathbf{u}}{dt} = \frac{\hat{d}\mathbf{u}'}{dt} + 2\bar{\mathbf{\Omega}} \times \mathbf{u}' + \bar{\mathbf{\Omega}} \times \bar{\mathbf{\Omega}} \times \mathbf{r}'$$
(3)

120 where $\hat{d}\mathbf{u}'/dt$ is the relative acceleration. The second term on the right of (3) is a 121 Coriolis-like term, which in the equations of motion adds to the Coriolis term arising 122 from the rotation of the Earth yielding $(f + \overline{\zeta})\hat{\mathbf{z}} \times \mathbf{u}'$. Thus, for such an observer moving 123 with the background flow, such as a drifting balloon, one would have an effective

124 frequency f_{eff} given by

$$125 f_{eff} = f + \overline{\zeta} (4)$$

126 To examine how the dispersion relation is changed we consider the equations of127 motion in the Earth-fixed frame. These are

128
$$\frac{du}{dt} = \frac{Du}{Dt} - \frac{uv}{r} = fv - \frac{1}{\rho} \frac{\partial p}{\partial x}$$
(5)

129
$$\frac{dv}{dt} = \frac{Dv}{Dt} + \frac{u^2}{r} = -f u - \frac{1}{\rho} \frac{\partial p}{\partial y}$$
(6)

130 where $D/Dt = \partial/\partial t + u \partial/\partial x + v \partial/\partial y + w \partial/\partial z$, *u*, *v* and *w* are, respectively, the

131 azimuthal, radial and vertical components of the velocity, ρ is density and p is pressure.

132 Also, x and y are, respectively, the curvilinear coordinates defined by $dx = rd\theta$

133 and dy = dr, where r, θ and z are, respectively, the radial, azimuthal and vertical

134 coordinates. Let the horizontal background flow be in solid body rotation as above and

135 write the equations of motion for a system rotating with the angular speed of the

136 background flow. The linearized forms of (5) and (6) are

137
$$\frac{\overline{D}u'}{Dt} + w'\frac{\partial\overline{u}}{\partial z} = (f + 2\overline{\Omega})v' - \frac{1}{\overline{\rho}}\frac{\partial p'}{\partial x}$$
(7)

138
$$\frac{\overline{D}v'}{Dt} = -(f + 2\overline{\Omega})u' - \frac{1}{\overline{\rho}}\frac{\partial p'}{\partial y}$$
(8)

139 where $\overline{D}/Dt = \partial/\partial t + \overline{u}\partial/\partial x$, overbars denote the background flow in solid body 140 rotation and primes denote departures therefrom. For this system, the dispersion relation based on the full quasi-static system that includes the heat and continuity equations (seethe Appendix) is

143
$$m^{2} = \frac{N^{2}}{\omega_{I}^{2} - f_{eff}^{2}} k^{2} - \frac{1}{4H^{2}}$$
(9)

144 where f_{eff} is given by (4), and $\overline{D} / Dt = \omega_1$ where ω_1 is the intrinsic frequency.

145 For $\omega_I^2 < f_{eff}^2$, m^2 is negative and the wave is evanescent. Thus the inertial-gravity 146 wave spectrum measured by a balloon is cut off for intrinsic frequencies below the 147 effective inertial frequency.

148 We show in the appendix that for a more general combination of shear and curvature $\overline{\zeta}_a - \overline{\zeta}/2 \le f_{eff} \le \overline{\zeta}_a + \overline{\zeta}/2$, where $\overline{\zeta}_a = f + \overline{\zeta}$ is the absolute vorticity of the 149 150 background flow. For pure shear (locally approximated as linear shear) with no curvature, wave motion normal to the direction of shear gives $f_{eff} = \overline{\zeta}_a - \overline{\zeta}/2$, while motion along 151 the direction of shear gives $f_{eff} = \overline{\zeta}_a + \overline{\zeta}/2$. When the motion approaches a direction 152 midway between these two extremes $f_{eff} \rightarrow \overline{\zeta}_{a}$. This is to be compared with the result of 153 Kunze (1985) where $f_{eff} \approx \overline{\zeta}_a - \overline{\zeta}/2$ irrespective of wave direction. Pure solid-body 154 rotation gives $f_{eff} = \overline{\zeta}_{a}$, in agreement with (5). Accordingly, for measurements made on a 155 balloon drifting with the wind, we expect the spectra derived from an ensemble of waves 156 with a range of directionality to show peak energy between $\omega_I = \overline{\zeta}_a - \overline{\zeta}/2$ and 157 $\omega_I = \overline{\zeta}_a + \overline{\zeta}/2$ rather than near *f*. 158

159 3. Data Description

160 Beginning on 5 September 2005, the VORCORE campaign released nineteen SPBs with 161 10 m diameters and eight balloons with 8.5 m diameters from McMurdo, Antarctica 162 (77.5° S, 166.4° E); they drifted near 50 hPa and 70 hPa, respectively. The mean flight 163 duration of the twenty-seven balloons was 59 days and the longest flight duration was 164 109 days (see Hertzog et al. 2007). 165 Each SPB carried temperature and pressure sensors and a Global Positioning System 166 (GPS) receiver. Balloon positions were recorded every 15 minutes with a position 167 accuracy of 15 m so that wind speeds could be estimated with accuracy greater than 0.2 m s⁻¹ (Hertzog et al. 2007). The geographical sampling of the Antarctic vortex core was 168 very good with best sampling in the 60° S-80° S latitude band and 60° W-120° E 169 170 longitude sector since the vortex had a tendency to be centered off the pole towards South 171 America (Hertzog et al. 2007). 172 Evaluation of general conditions in the polar vortex, required to understand and 173 interpret balloon data, was done using the Modern Era Retrospective-analyses for

174 Research and Applications (MERRA) tool produced by NASA. MERRA products are

175 produced at 3 hour intervals with a spatial resolution of $\frac{1}{2}$ degree latitude, $\frac{2}{3}$ degree

176 longitude and 72 pressure levels to 0.01 hPa (approximately 80 km altitude). We compute

177 the absolute vorticity using the MERRA horizontal winds to obtain vorticity maps for

178 each 3-hour interval, then interpolate to find the absolute vorticity at the time and

179 location of each balloon measurement. An example vorticity map for 20 October, 2005

180 derived from MERRA horizontal winds at 52 hPa is presented in the top panel of Figure

1. The values of $\overline{\zeta}$ within the Antarctic polar vortex approach -1 x 10⁻⁴ s⁻¹, a significant 181 fraction of $f(-1.4 \times 10^{-4} \text{ s}^{-1} \text{ at } 70^{\circ}\text{S})$. An example showing the range of absolute vorticity 182 183 (or effective inertial frequencies assuming pure solid body rotation) inside the vortex is shown in the bottom panel of Figure 1. Inside the vortex, the $|\overline{\zeta}_a|$ is typically ~ 1.8 x 10⁻⁴ 184 s⁻¹, approximately 25% higher than |f| at these latitudes. Henceforth all references to 185 values of $\overline{\zeta}, \overline{\zeta}_a, f$ and f_{eff} , including minima and maxima are in the sense of the 186 187 absolute values. Not also that in the following discussion results of the balloon analysis 188 (FFT, wavelet) are given in cycles/s and vorticities in angular frequencies (which include 189 a factor of 2π). This convention is chosen to be consistent with standard practice when 190 discussing vorticity while also allowing intuitive conversion between frequency and 191 period for wave data.

192 4. Data Analysis and Results

a. Spectral analysis

In this section we present a spectral analysis of zonal wind derived from SPB location
data showing a frequency shift of the spectral peak. The SPB flights used in the analysis
that follows spanned the October through November period, when, except for late
November, the polar vortex remained well-defined and strong. In 2005, the vortex was
very stable in September and October, moved off the pole in November and broke up in
early December (Hertzog et al. 2007).

Zonal wind velocities were derived from the SPB measurements as described in
Hertzog et al. (2007). Fourier analysis of the zonal wind velocity over two-week periods

was performed individually for each balloon and then averaged. The results, presented in Figure 2, show a distinct spectral peak at ~0.10 hr⁻¹, well separated from the frequency of the semidiurnal tide (indicated by the green line), that persists from early October through November. The red hatched area shows the range of inertial frequencies *f* for all balloons in the two week period; effective inertial frequencies for pure solid body rotation,

207 $f_{eff} = \overline{\zeta}_{a}$, for each two-week period are indicated by the black hatched area in Figure 2.

208 For each two-week period considered, the spectral peak falls within the range of solid-

209 body effective inertial frequencies, and generally lies outside the range of the frequencies

210 found for *f*. The peak shifts toward the inertial frequency range in late December, which

211 is consistent with the breakup of the vortex.

212 b. Wavelet Analysis

213 The intermittent nature of inertial waves suggests wavelet analysis as a means to explore 214 the temporal behavior of the zonal wind spectra. The time series from each balloon was 215 analyzed with Morlet wavelets in order to identify the spectral features as a function of 216 time (Torrence and Compo 1998). The wavelet analysis confirmed that the dominant peak in the spectrum occurred near 0.1 hr⁻¹, as indicated by the Fourier analysis discussed 217 above. The peak wavelet power was generally found to lie between $\sim 0.08 - 0.13$ hr⁻¹. 218 219 Figure 3 shows the results of a wavelet analysis for three sample balloon trajectories. 220 Also shown are the values of the inertial frequency at the balloon location f and the local

value of $\overline{\zeta}_a$ (f_{eff} for the case of pure solid body rotation). Local values of $\overline{\zeta}_a$ are

222 determined by interpolating MERRA vorticity to each balloon trajectory as a function of

223 location and time at the 52 hPa pressure level. Figure 3 shows that there is significantly

better agreement between the location of the spectral peak and $\overline{\zeta}_a$ (black curves), than 224 the frequency corresponding to f (red curves), particularly in October and early 225 November. Several instances of significant spectral peaks on the low frequency side of f_{eff} 226 227 seen in Balloon 2 during November, when a significant oscillation occurs near 20 hours 228 (the lowest plotted frequency), is probably a manifestation of the diurnal tide. There are a number of instances in Figure 3 for which a cutoff near $\overline{\zeta}_a$ is not 229 230 apparent. Results of a statistical analysis to examine the difference between the 231 frequency of the measured spectral peak and the local values of f are presented in Figure 232 4. The frequency of maximum wavelet power is determined for each balloon 233 measurement, e.g., the frequency of the peak wavelet power as a function of time for the wavelet spectra shown in Figure 3. The results, binned in 0.05 s^{-1} intervals, are presented 234 235 in Figure 4, which shows the number of balloon measurements as a function of difference between measured peak frequency f_m and inertial frequency f. Note that wave period, 236 237 rather than frequency, is plotted since the wavelet algorithm used for the spectral analysis 238 returns wavelet power as a function of period rather than frequency and is the natural way 239 to bin the results. Statistics are presented for each two-week period in October and 240 November, since the wavelet analysis shown in Figure 3 suggests that the spectral peak diverges from pure solid body rotation $f_{eff} = \overline{\zeta}_a$ sometime in November. 241

The distribution of balloon measurements presented in Figure 4 shows peaks near ζ_a as well as peaks displaced somewhat from $\overline{\zeta}_a \pm \overline{\zeta}/2$ toward $\overline{\zeta}_a$. The spectral peak of zonal wind measurements for October is generally consistent with that expected for pure solid body rotation $\overline{\zeta}_a$ with secondary contributions near $\overline{\zeta}_a \pm \overline{\zeta}/2$. The vortex was 246 observed to weaken, deform and move off the pole during November. The main peak in the occurrence frequency shifts toward $\overline{\zeta}_a - \overline{\zeta}/2$ in the first half of November and in the 247 second half the main part of the distribution is found between $\overline{\zeta}_a - \overline{\zeta}/2$ and $\overline{\zeta}_a$ with a 248 slight bias toward $\overline{\zeta}_a - \overline{\zeta}/2$. In section 5 it is shown that the relative vorticity can be 249 250 expressed as the sum of a solid body component and a shear component. The displacement away from $\overline{\zeta}_a$ is consistent with an increase in the relative contribution of 251 252 the non-solid body component. The high-frequency tail is associated with power from 253 sporadic high-frequency gravity waves that occasionally cause peak amplitudes at 254 frequencies higher than the inertial frequency, and is consistent with the results from the Fourier analysis presented earlier in Figure 2. 255

5. Discussion

We show in the appendix that for a fairly general combination of shear and rotation $\overline{\zeta}_a - \overline{\zeta}/2 \le f_{eff} \le \overline{\zeta}_a + \overline{\zeta}/2$, where $\overline{\zeta}_a = f + \overline{\zeta}$ is the absolute vorticity of the background state. In a "natural" coordinate system where the x-axis is along the basic flow velocity vector and the y-axis is in the orthogonal direction consistent with a right-handed system the vorticity is written (Holton, 1972)

262
$$\overline{\zeta} = U \frac{\partial \beta}{\partial s} - \frac{\partial U}{\partial y}$$
(10)

where $\partial \beta / \partial s$ is the rate of change of the angle β between the x-axis and the tangent to the streamline as a function of the distance *s* along the streamline. In terms of the local radius of curvature *r*

266
$$\overline{\zeta} = \frac{U}{r} - \frac{\partial U}{\partial y}$$
(11)

where r is positive for cyclonic motion and U is the velocity component in the xdirection.

Since the horizontal scale k^{-1} of typical gravity waves (~a few tens of kilometers or less) is much less than the scale of variation of the background flow (~ a few hundred kilometers or more) we can expand the wind field to first order using a Taylor expansion of the rotational part of the wind field at the balloon position as $U_{\zeta}(y) = U_0 + Ay$ and $V_{\zeta}(x) = Bx$, whence

$$\overline{\zeta} = B - A \tag{12}$$

When A = -a and B = a one obtains the result for solid body rotation $\overline{\zeta} = 2a$ (see Appendix). In terms of (11), $a = (U/r)_0$ and $\overline{\zeta} = 2(U/r)_0$. More generally we can write $A = a + \delta a$ and express (11) in terms of the sum of vorticity from solid body rotation and the excess shear in addition to the shear that is consistent with solid body rotation as follows

280
$$\overline{\zeta} = 2\frac{U}{r} + \delta\overline{\zeta}$$
(13)

281 where
$$\delta \overline{\zeta} = -\delta a = -(U/r + \partial U/\partial y)_0$$
.

In the appendix we show that for pure shear with no curvature, wave motion normal to the direction of shear gives $f_{eff} = \overline{\zeta}_a - \overline{\zeta}/2$, while wave motion along the direction of shear gives $f_{eff} = \overline{\zeta}_a + \overline{\zeta}/2$. When the wave motion approaches a direction midway between these two extremes $f_{eff} \rightarrow \overline{\zeta}_{a}$. This is to be compared with the result of Kunze (1985) where $f_{eff} \approx \overline{\zeta}_{a} - \overline{\zeta}/2$, irrespective of the direction of wave motion. Pure solid body rotation gives $f_{eff} = \overline{\zeta}_{a}$ in agreement with (4). Accordingly, for measurements made on a balloon drifting with the wind, we expect the spectra derived from an ensemble of waves with a range of directionality to show peak energy between $\omega_{L} = \overline{\zeta}_{a} - \overline{\zeta}/2$ and $\omega_{L} = \overline{\zeta}_{a} + \overline{\zeta}/2$ rather than near *f*.

291 An example of the relative contribution from solid-body rotation and shear excess is 292 presented for 20 October, 2005 in Figure 5. The total vorticity for this date was depicted 293 previously in Figure 1. The top two panels of Figure 5 show the curvature and shear 294 vorticity, U/r and $\partial U/\partial v$, respectively, as discussed earlier in this section. The 295 contribution from solid body rotation 2U/r is shown in the lower left panel of Figure 5 and the excess shear vorticity $-(\partial U/\partial y + U/r)$ in the lower right panel. Clearly, on this 296 297 date the dominant component of the relative vorticity is from solid body rotation, which suggests an effective inertial frequency near $\overline{\zeta}_a$. 298

299 The temporal change of the effective inertial frequency depicted in Figure 4 suggests 300 that the relative contributions of solid body and shear vorticity change between the 301 October and November observation periods. A statistical analysis of the ratio of the solid 302 body to shear vorticity for each two week time period is presented in Figure 6. Solid 303 body and shear vorticity were calculated from MERRA data, and then interpolated to the 304 balloon locations. Figure 6 shows the percentage of balloon measurements having the 305 indicated solid body to shear vorticity ratio. The solid body component clearly dominates 306 throughout October, where nearly 14% of the balloon observations showed dominant

307 solid body rotation, as compared to approximately 4% of observations for which the 308 shear component of the vorticity dominates. From this, it would be expected that the 309 main peak in the occurrence frequency for the effective inertial frequency for October would be shifted only slightly off $\overline{\zeta}_a$, as is shown in Figure 4. The existence of two 310 311 dominant peaks, one centered near zero and the other near -2, is informative. The first 312 peak is consistent with large shear and negligible curvature. These conditions can exist 313 near the boundaries of a vortex where, even though the curvature may not be small, the 314 shear may be very large in comparison (see Figure 5). The second peak corresponds to 315 negligible excess shear. These conditions are consistent with conditions that cover more 316 extensive areas in the central part of the vortex.

317 By the end of November, however, the relative contributions of solid body and shear 318 vorticity are nearly equal, with the average value of the effective inertial frequency expected to be shifted away from $\overline{\zeta}_a$ toward either $\overline{\zeta}_a - \overline{\zeta}/2$ or $\overline{\zeta}_a + \overline{\zeta}/2$ depending on 319 320 wave directionality. The statistics presented in Figure 4 show that the former is favored. 321 The results presented in Figure 4 suggest that a large fraction of the waves measured by 322 the balloons are propagating in a direction not too different from that of the wind. The shift toward $\overline{\zeta}_a - \overline{\zeta}/2$ is consistent with the wavenumber vector aligned with the wind in 323 324 laterally sheared flow, such as near the boundaries of the vortex. An inspection of the 325 balloon trajectories indicates that balloons tend to be found near the vortex boundary 326 much of the time in late November. These comparisons show that the solid-body rotation 327 component dominates the absolute vorticity for much of October, but by early November 328 the excess shear component becomes stronger as the vortex deforms and weakens.

329 6. Summary and conclusions

330

331 used vorticity fields from the MERRA analysis to identify and interpret spectral features 332 of low-frequency inertial gravity waves recorded by VORCORE balloons in the Antarctic 333 stratosphere. Balloon spectra were derived using both Fourier and wavelet analyses. We 334 have shown that the spectral peak of wind measurements made on balloons drifting with 335 the wind is shifted to frequencies more than 25% higher than the local inertial frequency. 336 Frequency shifts have been reported in other works but were either made in a non-337 intrinsic frame (Mori et al., 1990) or showed significantly smaller shifts (Hertzog et al., 338 2002). The exceptionally strong Antarctic polar vortex allowed identification of the peak 339 as that corresponding to a shift in the inertial frequency f (Coriolis parameter) by the relative vorticity $\overline{\zeta}$. We interpret $f_{e\!f\!f}$ as the inertial frequency in a coordinate frame 340 341 moving with the basic flow. 342 We study the case in which the flow locally can be written as the superposition of solid body rotation and simple shear. The solid body contribution gives $f_{eff} = f + \overline{\zeta}$ 343 344 independent of wave directionality. The shear contribution gives values $\overline{\zeta}_a - \frac{1}{2}\overline{\zeta} \le f_{eff} \le \overline{\zeta}_a + \frac{1}{2}\overline{\zeta}$ depending on wave direction. Our observations are consistent 345 with a spectrum of waves contributing to a spread of f_{eff} , with the distribution broadly 346 consistent with $f_{eff} \approx \overline{\zeta}_a$ during October and early November, but peaked closer to 347 $f_{eff} \approx \overline{\zeta}_a - \frac{1}{2}\overline{\zeta}$ in late November as the vortex weakened. 348

We have applied spectral methods to analyze wind fields from SPB measurements, and

A possible source for a peak at frequencies higher than f is waves generated by
fronts and jets. These waves have frequencies near 1.4 f [O'Sullivan and Dunkerton,
1995; Plougonven and Snyder 2005a,b]. However these frequencies are significantly
higher than the inertial peak we observe. We have examined the possibility that the 0.1
hr ⁻¹ peak is representative of the semidiurnal tide Doppler shifted by balloon motion, but

- 354 found this effect to be too small to account for the observed shift. Nor do we find the
- 355 large-scale coherency expected for a tide. Finally, we have examined pressure variations
- and find minimal power in the $0.08-0.12 \text{ hr}^{-1}$ band (not shown here). This is a
- 357 characteristic feature of inertial waves.
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APPENDIX

368 In this appendix we derive expressions for the inertial frequency in a flow combining 369 rotation and linear shear. The latter should give a reasonable representation of the shear 370 experienced by inertial gravity waves in a slowly spatially varying background wind 371 field. We show that depending on the flow configuration and wave directionality

372 $f_{eff} = \overline{\zeta}_a + \frac{1}{2}n\overline{\zeta}$, where n = -1, 0, 1 and where $\overline{\zeta}_a = f + \overline{\zeta}$ is the absolute vorticity. 373 Before we proceed to consider inertia gravity waves in a stratified atmosphere we 374 consider the simple case of solid body rotation for pure inertial waves in Cartesian

375 geometry.

380

376 1. Inertial waves in solid body rotation (Cartesian formulation)

377 In Cartesian coordinates cyclonic solid body rotation is given by $U(y) = U_0 - ay$ and

- 378 $V(x) = V_0 + ax$, where $\mathbf{U} = (U, V)$ is the basic horizontal flow. Pure inertial motion on a
- 379 background state in solid body rotation is given by

$$\frac{\partial u'}{\partial t} + U \frac{\partial u'}{\partial x} + V \frac{\partial u'}{\partial y} - (a+f)v' = 0$$

$$\frac{\partial v'}{\partial t} + U \frac{\partial v'}{\partial x} + V \frac{\partial v'}{\partial y} + (a+f)u' = 0$$
(1.1)

381 This generates the vorticity equation

382
$$\frac{\overline{D}\zeta'}{Dt} + (f + \overline{\zeta})\delta' = 0$$
(1.2)

383 and the divergence equation

384
$$\frac{\overline{D}\delta'}{Dt} - \left(f + \overline{\zeta}\right)\zeta' = 0 \tag{1.3}$$

385 where
$$\zeta = -\partial u/\partial y + \partial v/\partial x$$
, $\delta = \partial u/\partial x + \partial v/\partial y$,

386
$$\frac{\overline{D}}{Dt} = \frac{\partial}{\partial t} + U \frac{\partial}{\partial x} + V \frac{\partial}{\partial y}$$
(1.4)

and $\overline{\zeta} = 2a$. Elimination of the divergence between (2) and (3) gives

388
$$\frac{\overline{D}^{2}\zeta'}{Dt^{2}} + \left(f + \overline{\zeta}\right)^{2}\zeta' = 0$$
(1.5)

389 whence

$$390 \qquad \qquad \omega_I^2 = \left(f + \overline{\zeta}\right)^2 \tag{1.6}$$

391 or
$$f_{eff} = f + \overline{\zeta} = \overline{\zeta}_a$$
.

This agrees with the results obtained in section 4.

Note that in deriving (4) we assumed that the advective terms in (1.2) and (1.3) were locally constant. This differs from assuming that the advective terms are locally constant from the onset (Kunze , 1985). It is instructive to look at the vorticity equation when the advective terms in (1.1) are forced to be constant. One then obtains the incorrect result

397
$$\frac{\overline{D}\zeta'}{Dt} + (f + \overline{\zeta}/2)\delta' = 0$$
(1.7)

This example shows that when considering a system where rotational effects are important it is essential to work with equations that preserve the correct form of the vorticity equation. It also shows that assuming that the advection terms are locally constant in the divergence and vorticity equations (1.2) gives the correct result

 $402 \qquad f_{eff} = f + \overline{\zeta} \; .$

403 2. Inertial gravity waves

We work with the vorticity and divergence equations in lieu of the horizontal momentum equations for the reasons discussed in the previous section. The equations in the logpressure system are (Andrews et al., 1987).

407
$$\frac{\overline{D}\zeta'}{Dt} + (f + \overline{\zeta})\delta' = 0$$
(2.1)

408
$$\frac{\overline{D}\delta'}{Dt} - 2\overline{\zeta}\frac{\partial v'}{\partial x} - f\zeta' = -\frac{1}{2}$$

$$\frac{D\delta}{Dt} - 2\bar{\zeta}\frac{\partial v}{\partial x} - f\zeta' = -\nabla^2 \varphi'$$
(2.2)

409
$$\frac{\partial w'}{\partial z} - w' + \delta' = 0 \tag{2.3}$$

410
$$\frac{\overline{D}}{Dt}\frac{\partial\varphi'}{\partial z} + Sw' = 0$$
(2.4)

411 where
$$z = -\log(p/p_0)$$
, $w = \dot{z}$, $S = RT \log \overline{\theta}/dz$, and $\phi' = g\eta'$ and where η' is the
412 disturbance height of pressure surfaces.

413 Let the velocity be written in terms of the stream function ψ and velocity

potential χ , whence 414

415
$$u' = -\frac{\partial \psi'}{\partial y} + \frac{\partial \chi'}{\partial x}$$
(2.5)

416
$$v' = \frac{\partial \psi'}{\partial x} + \frac{\partial \chi'}{\partial y}$$
(2.6)

This gives 417

418
$$\frac{\overline{D}\nabla^2 \psi'}{Dt} + \left(f + \overline{\zeta}\right) \nabla^2 \chi' = 0$$
 (2.7)

419
$$\frac{\overline{D}\nabla^{2}\chi'}{Dt} - 2\overline{\zeta} \frac{\partial}{\partial x} \left(\frac{\partial \psi'}{\partial x} + \frac{\partial \chi'}{\partial y} \right) - f\nabla^{2}\psi' = -\nabla^{2}\varphi' \qquad (2.8)$$

420
$$\frac{\partial w'}{\partial z} - w' + \nabla^2 \chi' = 0$$
 (2.9)

421 To transform out the exponential growth with altitude one defines a new set of422 variables

423
$$\xi' = \hat{\xi} \exp(z/2)$$
 (2.10)

424 where ξ is any dependent variable. Then (2.9) becomes

425
$$\left(\frac{\partial}{\partial z} - \frac{1}{2}\right)\hat{w} + \nabla^2 \hat{\chi} = 0$$
 (2.11)

426 and (2.4) becomes

427
$$\frac{\overline{D}}{Dt}\left(\frac{\partial}{\partial z} + \frac{1}{2}\right)\ddot{\boldsymbol{\varphi}} + S\dot{\boldsymbol{\varphi}} = 0$$
(2.12)

428 otherwise one simply replaces primes with carets in (2.7) and (2.8).

429 To obtain a dispersion relation we eliminate $\hat{\psi}$ in favor of $\hat{\chi}$ using (7), eliminate $\hat{\chi}$ 430 in favor of \hat{w} using (2.11) and finally eliminate $\hat{\phi}$ in favor of \hat{w} using (2.12). Assuming 431 solutions of the form

432
$$\left(\frac{\partial}{\partial x}, \frac{\partial}{\partial x}, \frac{\partial}{\partial x}, \frac{\bar{D}}{Dt}\right) = \left(-ik, -il, -im, i\omega_{l}\right)$$
(2.13)

where *m* is the nondimensional vertical wavenumber in the log-pressure system gives thedispersion relation

435
$$m^{2} = \frac{Sk_{H}^{2}}{\omega_{l}^{2} - (f + \overline{\zeta})^{2} - \overline{\zeta}(f + \overline{\zeta})(k^{2} - l^{2})/k_{H}^{2} + i2\omega_{l}\overline{\zeta}kl/k_{H}^{2}} - \frac{1}{4} \qquad (2.14)$$

436 where $k_H^2 = k^2 + l^2$. We have assumed that $\overline{\delta} = 0$. For low-frequency waves for which 437 $m^2 >> 1$, (2.14) may be written

438
$$m^{2} = \frac{Sk_{H}^{2}}{\omega_{l}^{2} - (f + \overline{\zeta})^{2} - \overline{\zeta}(f + \overline{\zeta})(k^{2} - l^{2})/k_{H}^{2} + i2\omega_{l}\overline{\zeta}kl/k_{H}^{2}}$$
(2.15)

439 The denominator in (2.14) and (2.15)

440
$$\Delta = \omega_I^2 - \left(f + \overline{\zeta}\right)^2 - \overline{\zeta} \left(f + \overline{\zeta}\right) \left(k^2 - l^2\right) / k_H^2 + i2\omega_I \overline{\zeta} kl / k_H^2 \qquad (2.16)$$

441 is just the dispersion relation for pure inertial waves when $\Delta = 0$. This justifies the

442 simpler treatment when Δ is real. When Δ is complex we need the full dispersion

443 relation to interpret what this means (it does not mean that ω_1 is complex).

444 3. Inertial gravity waves in linear shear

445 As in section 4, we approximate the shear over the dimensions of a pure inertial wave in 446 terms of linear shear. Let $U(y) = U_0 + ay$ and $V(y) = V_0$, where U_0 and V_0 are constants, 447 then

$$\frac{\overline{D}u'}{Dt} - (f - a)v' = 0$$

448

$$\frac{\bar{D}v'}{Dt} + f u = 0$$

449 The vorticity equation is

450
$$\frac{\overline{D}\zeta'}{Dt} + \left(f + \overline{\zeta}\right)\delta' = 0 \tag{3.2}$$

451 The divergence equation is (Salmon, 1998)

452
$$\frac{\overline{D}\delta'}{Dt} - 2J(u,v) - f\zeta' = 0$$
(3.3)

453 The linearized Jacobian is

(3.1)

454
$$J(u,v) = -\frac{\partial}{\partial y}(u'+U)\frac{\partial}{\partial x}(v'+V) = -\frac{\partial U}{\partial y}\frac{\partial v'}{\partial x} = \overline{\zeta}\frac{\partial v'}{\partial x}$$
(3.4)

455 Using (3.4) in (3.3) gives

456
$$\frac{\overline{D}\delta'}{Dt} - 2\overline{\zeta} \frac{\partial v'}{\partial x} - f\zeta' = 0$$
(3.5)

457 We consider three special cases, viz., $\theta = 0$, $\pi/4$, $\pi/2$ corresponding to l=0, k=l and k=0.

458 3.1. PROPAGATION NORMAL TO THE SHEARED DIRECTION

459 With $\partial/\partial y = -il = 0$, $\zeta' = \partial v'/\partial x$, and (3.5) becomes

$$\frac{\overline{D}\delta'}{Dt} - \left(f + 2\overline{\zeta}\right)\zeta' = 0 \tag{3.6}$$

460

461 Eliminating the divergence between (3.2) and (3.6) gives

462
$$f_{eff} = \sqrt{\left(f + \overline{\zeta}\right)\left(f + 2\overline{\zeta}\right)} \approx \left(f + \overline{\zeta}\right) + \frac{1}{2}\overline{\zeta}$$
(3.7)

463 This agrees with (2.16) with l = 0 and $\Delta = 0$.

464 3.2. PROPAGATION ALONG THE SHEARED DIRECTION

465 With $\partial/\partial x = -ik = 0$, (3.5) becomes

$$466 \qquad \qquad \frac{\bar{D}\delta'}{Dt} - f\zeta' = 0 \tag{3.8}$$

467 Eliminating the divergence between (3.2) and (3.8) gives

468
$$f_{eff} = \sqrt{f\left(f + \overline{\zeta}\right)} \approx \left(f + \overline{\zeta}\right) - \frac{1}{2}\overline{\zeta}$$
(3.9)

469 This agrees with (2.16) with k = 0 and $\Delta = 0$.

3.3. PROPAGATION AT 45° TO THE SHEARED DIRECTION

For this case we use the more general theory for inertial gravity waves for the same basicstate linear shear. Equation (2.16) may be rewritten in terms of wave direction as

473
$$\Delta = \omega_I^2 - \left(f + \overline{\zeta}\right)^2 + \overline{\zeta}\left(f + \overline{\zeta}\right)\cos 2\theta + i\omega_I\overline{\zeta}\sin 2\theta \qquad (3.10)$$

474 where θ is the direction of propagation with respect to the x-axis (i.e., $\cos \theta = k/k_H$).

475 Propagation midway between propagation along and normal to the shear (l = k) gives

476
$$\Delta = \omega_l^2 - \left(f + \overline{\zeta}\right)^2 + i\omega_l\overline{\zeta}$$
(3.11)

477 In this case there is no singularity (value of ω_i for which $\Delta = 0$), rather there is a

478 minimum where the real part of m maximizes. The real part of m may be written as

479
$$m_{r} = \frac{-S^{\frac{1}{2}}k_{H}}{\left[\left(\omega_{I}^{2} - \overline{\zeta}_{a}^{2}\right)^{2} + \omega_{I}^{2}\overline{\zeta}^{2}\right]^{\frac{1}{4}}}\cos(\alpha/2)$$
(3.12)

480 where $\alpha = \tan^{-1} \left(\omega_I \overline{\zeta} / \left(\omega_I^2 - \overline{\zeta}_a^2 \right) \right)$ and the minus sign is chosen to give upward energy

481 propagation. The maximum absolute value of m_r occurs for $\omega_I = \overline{\zeta}_a$ and

482
$$m_r = \frac{-S^{\frac{1}{2}}k_H}{\sqrt{\overline{\zeta}_a\overline{\zeta}}}\cos(\pi/4)$$
(3.13)

483 For reasonable background values $m_r \sim 2 \times 10^2$ corresponding to very short vertical 484 wavelengths (a small fraction of a scale height). Such short wavelength near inertial 485 waves would almost certainly be absorbed by scale dependent diffusion (i.e., cutoff).

3.4. RELATION TO SOLID BODY ROTATION

Solid body rotation gives wave propagation in flow that is simultaneously sheared along and normal to the direction of propagation. If one averages the contribution from each direction using (3.7) and (3.9) one obtains $f_{eff} = f + \overline{\zeta}$, in agreement with the known result (see (1.6)).

491 3.5 RELATION TO APPROACH OF KUNZE (1985)

492 Kunze (1985) considered inertial gravity waves in sheared flow and obtained the result 493 $f_{eff} \approx f + \overline{\zeta}/2$. The basic approach was to derive the dispersion relation by assuming at 494 the onset that the advection terms were locally constant. We have seen that for solid body 495 rotation this gives the result $f_{eff} = f + \overline{\zeta}/2$ when the known result is $f_{eff} = f + \overline{\zeta}$. For 496 propagation normal to the shear the approach of Kunze (1985) gives

497
$$\frac{\overline{D}\delta'}{Dt} - \overline{\zeta} \frac{\partial v'}{\partial x} - f\zeta' = 0$$
(3.10)

Whence $f_{eff} = \sqrt{f(f + \overline{\zeta})} \approx f + \frac{1}{2}\overline{\zeta}$ in contrast to (3.7). For propagation along the shear the approach of Kunze (1985) also gives $f_{eff} \approx f + \overline{\zeta}/2$ in agreement with (3.9). As we have argued, solid body rotation is the average of the contributions from the shear in each direction. Thus the incorrect result for solid body rotation is consistent with the result $f_{eff} \approx f + \overline{\zeta}/2$ obtained independent of whether the direction of propagation is normal to or along the sheared direction.

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